## Computer Graphics Worksheet Texturing and Color

Dr. Sergey Kosov Jacobs University Bremen

## Problem 1. Texturing

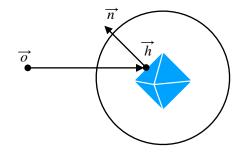
We would like to apply a texture image of resolution *width* x *height* to a sphere, such that the whole sphere will be covered with the whole texture. The sphere is located at point  $\vec{s}(x_0, y_0, z_0)$  and has radius *r*. The ray hits the sphere at point  $\vec{h}(x, y, z)$ . Please derive the texture coordinates (u, v) for point  $\vec{h}$ .

**Hint:** You can use the following formulas for transition from spherical to cartesian coordinate systems:

 $x = x_0 + r \sin \theta \cos \varphi$   $y = y_0 + r \sin \theta \sin \varphi$   $z = z_0 + r \cos \theta$ where  $\theta \in [0; \pi]$  and  $\varphi \in [0; 2\pi)$ 

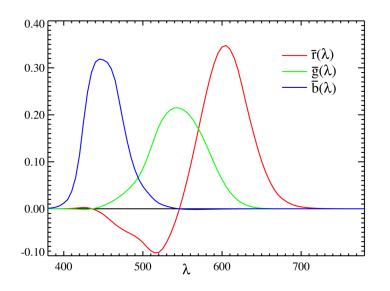
## Problem 2. Reflection Texturing

Given a ray hit-point  $\overrightarrow{h}$ , the origin of the ray from camera  $\overrightarrow{o}$  and the local surface normal  $\overrightarrow{n}$  (all expressed in world space), compute the pixel coordinates that have to be accessed in the reflection map texture. This texture is stored so that uv-coordinates map to spherical coordinates (normalized in [0, 1]).



## Problem 3. Color Models

On the image below you can see the CIE RGB color matching functions, which are the numerical description of the chromatic response of the *observer*. As you know these functions were estimated empirically during the color matching experiments:



Please explain with your own words

- a) How it is possible that the red curve becomes negative?
- b) How the negative values were estimated?