# Computer Graphics Worksheet Sampling and Reconstruction 

Dr. Sergey Kosov<br>Jacobs University Bremen

## Problem 1. Convolution vs Multiplication

The convolution of a function $f(x)$ with a second function $g(x)$ is defined as:
$(f * g)(x)=\int_{-\infty}^{\infty} f(t) \cdot g(x-t) d t$

The multiplication of two function is defined as the point-wise multiplication:
$(f \cdot g)(x)=f(x) \cdot g(x)$
The transformation of a signal $f(x)$ to Fourier space is given by:
$F(\omega)=\int_{-\infty}^{\infty} f(x) \cdot e^{-2 \pi i \omega x} d x$

We call $\mathscr{F}$ the operator mapping $f$ to Fourier space: $\mathscr{F}[f(x)]=F(\omega)$. Show that convolving in signal space is the same as multiplication in Fourier space:
$\mathscr{F}[(f * g)(x)]=\mathscr{F}[f(x)] \cdot \mathscr{F}[g(x)]$

## Problem 2. Fourier Transformation

Show that the Fourier transformation of the box function $B_{d}(x)$ is a sinc type function. The sinc function is defined as $\sin c(x)=\frac{\sin \pi x}{\pi x}$ and a definition of the Fourier transform can be found in the Problem 1.
$B_{d}(x)=\left\{\begin{array}{llr}0 & \text { for } & x \leq-d \\ 1 & \text { for } & -d<x<d \\ 0 & \text { for } & d \leq x\end{array}\right.$

## Problem 3. Triangle Filter

Show that reconstructing a signal that is sampled at sampling distance 1 with the triangle filter $T(x)$ is equivalent of performing linear interpolation.
$T_{1}(x)=\left\{\begin{array}{llr}0 & \text { for } & x<-1 \\ x+1 & \text { for } & -1 \leq x<0 \\ -x+1 & \text { for } & 0 \leq x<1 \\ 0 & \text { for } & 1 \leq x\end{array}\right.$

## Problem 4. Sampling Theory

Let $f(x)$ be an infinite signal that fulfils the Nyqvist property, thus the highest frequency of the signal is smaller than $\frac{1}{2 \Delta x}$ if $\Delta x$ is the sampling distance. Consider a regular sampling $f_{s}(x)$ of $f(x)$ with sample distance $\Delta x$.
a) Is an exact signal reconstruction of $f(x)$ possible? If so, why?
b) How has the reconstruction to be performed in image and Fourier space?

## Problem 5. Antialiasing

c) Describe what aliasing means in Fourier space.
d) Consider an infinite signal $f(x)$ and a regular sampling $f_{s}(x)$ with sampling distance $\Delta x$ that shows no aliasing artefacts. The sampling distance is now increased step by step until the first aliasing artefacts occur.
How can we best get an aliasing-free sampled signal from these samples? Describe the filter procedure in Fourier and signal space. You do not have to derive the exact filter kernels (but you can of course).

